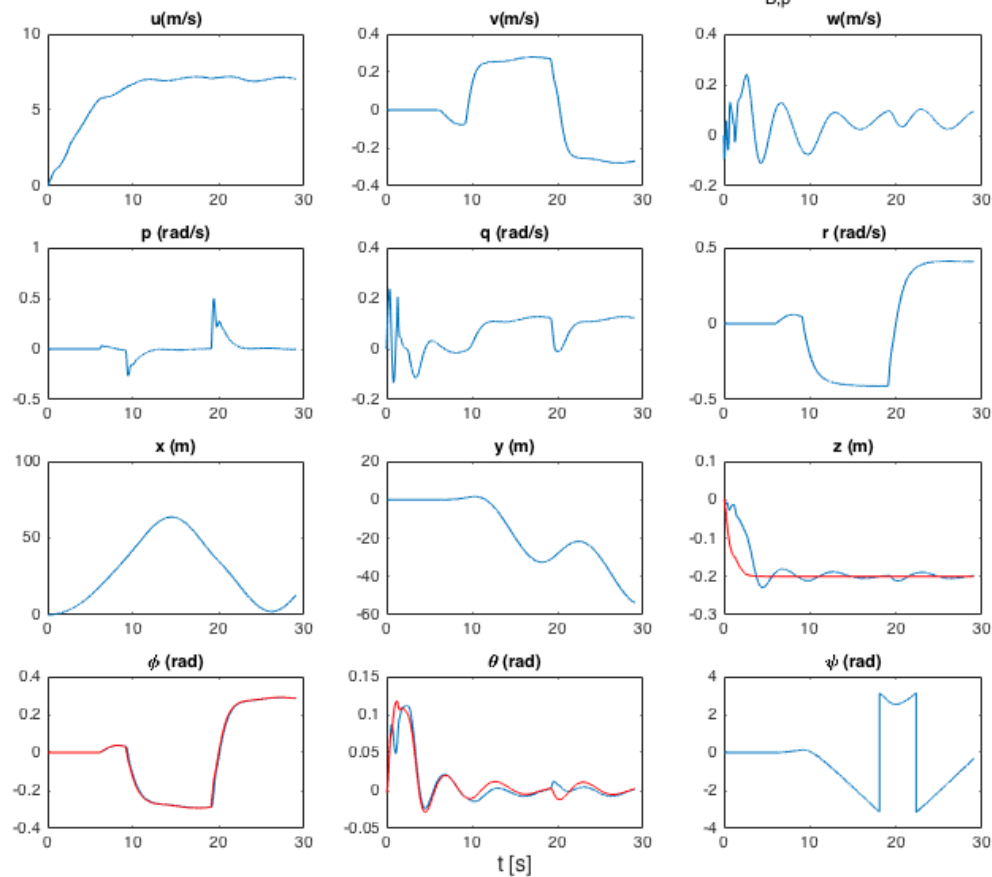


System states evolution, redundancy management, imposing $\delta_{B,p}^* = -0.1$ rad



System trajectory, $\delta_{B,p}^* = -0.1$ rad

